

# A Proposal to use ABS as a Proof of Concept Platform for New Theories

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# ABS and its Application's Domain

- Distributed software application  
(e.g., cloud computing, distributed work processing)
- Cyber physical systems  
(e.g., software updates for cars)
- Distributed business/operational processes  
(e.g., operational planning, railway operations)
- Formal systems  
(e.g, OS: multicore data access, memory models)
- Biological systems
- ...

# The Flexible framework of ABS

So far ABS has been able to closely represent the intended domain

- **User defined data types and functions:**  
allows to express and manipulate data for various domains
- **Synchronous and asynchronous communication:**  
helps to naturally describe interactions between objects/components
- **Cooperative scheduling:**  
naturally describe concurrent workflows.

# ABS as a Proof of Concept Platform

Can we use ABS as proof of concept platform for new theories?

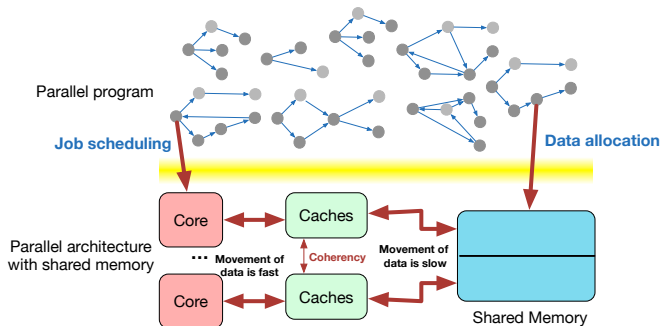
## Proof of Concept (POC)

- Demonstrate how a new concept/theory has the potential to be applied to real applications
- Test new concept/theory under certain assumptions and demonstrate their functionality
- Observe the functionality of a concept/theory when it is integrated into a model of an existing system
- Explore an emerging concept/theory and provide evidence to the potential stakeholders

Built an ABS executable model that gives an idea how a theory/concept could potentially work

# A Concrete New Concept: Location Types

## Problem Domain:



- Unnecessary movement of data affects performance
- Disconnection between locations for processing and locations of data

# Abstract representation of the main memory

Location		$L_x$		$L_y$			$L_z$				
Address	...	0x11cedf	...	0x11cee2	0x11cee3	...	0x11cee5	0x11cee6	...	0x11cee8	...
Value											

## Memory footprints:

- Use the idea of abstract locations in main memory to approximate reads and writes data access
- Develop a type system that uses locations to statically extract and describe how workflows interact with Memory

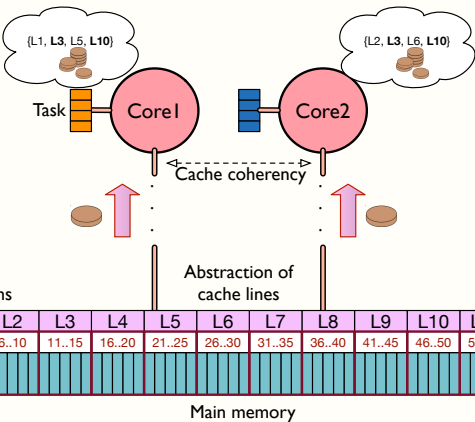
# Type system to predict data accesses

## Concurrent Execution

Pool of tasks

{ pink orange orange purple pink purple ... }

1. Take into account fetch and eviction
2. Penalty for fetches

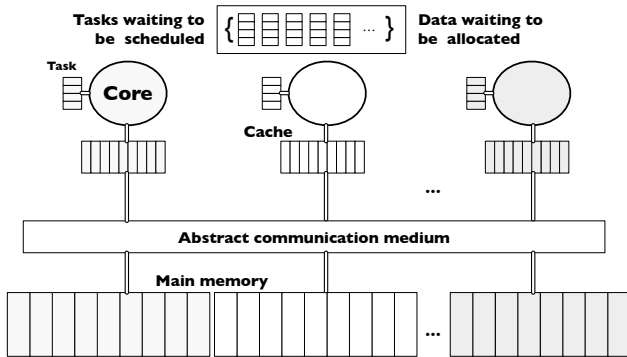


# Type Analysis

- Standard type system
  - Variables, pointers and addresses are in the right locations
  - Check that all locations are understood in the different tasks/processes
  - Check that references of variables are contained in only one location in main memory
  - Check that the state of the local data complies with the state in the main memory
- Advance behavioural types – "memory access footprints"
  - Check that the runtime system accesses locations as expected during execution (e.g., reading/writing)
  - Check that the cache memory (set of locations), changes as expected during execution
- Types at runtime - model based scheduling and allocation decisions
  - Can we make use of memory access footprints for scheduling and allocation?



# Starting point in ABS: A multicore layer of execution with coherent caches and shared memory



Can we build and use this layer as an API similar to the cloud API?

## Runtime application of Location Types

### Model of a software application

Static analysis for  
memory footprints

Source code with  
parallel workflow

Application-specific data allocation  
and task scheduling

Approximations of  
memory footprints

Tasks

Coordinated data allocators and task schedules

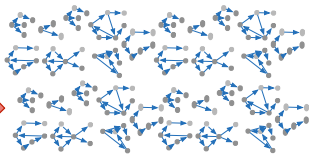
Infrastructure with concrete memory locations

### Model of a parallel architecture

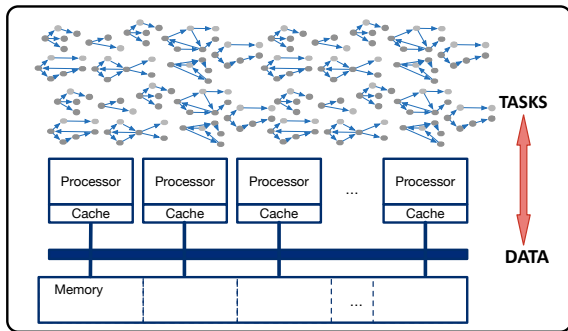
# Validation: simulations with measurements



Abstract



Collect measurements during simulations for comparisons



- **What is missing:** Visualisation targeting multicore execution
- **What is challenging:** how to relate the theory to the model?
  - Is it a one to one matching between the theory and the model?
  - can we develop a simulation/bisimulation relation method?
  - can we express it as properties to the proof system?

Can we use ABS as proof of concept platform for location types and their use for schedulers and allocators?

## Proof of Concept for *Location Types*

- Demonstrate how *Location Types* have the potential to be applied in parallel software
- Test *Location Types* under certain assumptions and demonstrate their functionality for schedulers and allocators
- Observe the functionality of *Location Types* when it is integrated into a model of a multicore architecture running parallel tasks.
- Explore *Location Types* and provide evidence to potential stakeholders

- **What is missing:**  
Visualisation in ABS targeting multicore execution
- **What is challenging:**  
how to relate the theory to the ABS model?
  - Is it a one to one matching between the theory and the model?
  - can we develop a simulation/bisimulation relation method?
  - can we express it as properties to the proof system?
- Are there other challenges?

THANK YOU